
MATHEMATICS 3Q

16 OCTOBER 2009

MIDTERM TEST

DR. N. KEVLAHAN

DURATION OF EXAM: 50 MINUTES

PLEASE SHOW ALL WORK

1. Consider polynomial interpolation at equally spaced points on the interval $[-1/4, 3/4]$ of the function

$$f(x) = \frac{1}{1 + 16x^2}.$$

- [4] (a) Will polynomial wiggle (i.e. Runge phenomenon) be a problem on this interval?
- [2] (b) Over what sub-interval of $[-1/4, 3/4]$ centred at $1/4$ is polynomial wiggle *not* a problem?
- [4] (c) How can one avoid polynomial wiggle entirely for *any* choice of interval?
- [4] 2. (a) Calculate the rate of convergence of Newton's method in one dimension for the case of both simple and multiple roots.
- [3] (b) How can one *accurately* estimate the rate and constant of convergence of an iterative method given the error at each iteration?
- [4] 3. (a) Show that the absolute condition number for the problem of finding the minimum x^* of a function $f(x)$ is

$$C = \sqrt{\frac{2}{\Delta b |f''(x^*)|}},$$

where Δb is the absolute *backward* error.

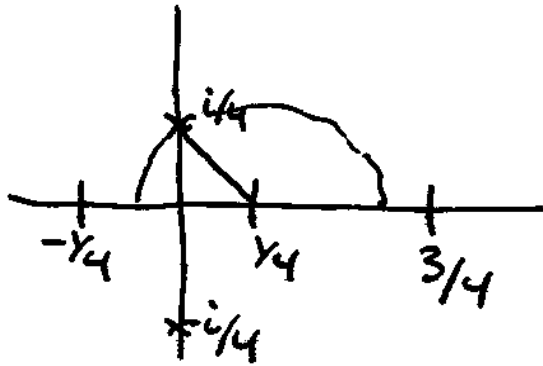
- [4] (b) If we use a floating point number system with 16 digits of accuracy, to how many digits of accuracy can we find the minimum of a function? [Hint: use your result from (a).]

[Total: 25]

THE END

Math 302: Test (2009)

1. (a) poles of $f(z)$ are at $z = \pm i/4$



\therefore Runge phenomenon is present outside interval $1/4 \pm \frac{1}{2\sqrt{2}}$

$$\text{or } [-0.1036, 0.6036]$$

\therefore Runge Phenomenon is a problem in $[-1/4, 3/4]$

(b) See (a): $[-0.1036, 0.6036]$

(c) one can use a suitable distⁿ of nodes (eg. Chebyshev) and as a stable algorithm for computing the weights (eg. barycentric).

Equally spaced points are the worst choice!

(2)

2. (a) Consider fixed point iteration

$$x_{k+1} = g(x_k) \quad \text{where } g(x) = x - \frac{f(x)}{f'(x)}$$

$$\begin{aligned} \rightarrow |x_{k+1} - x_*| &= |g(x_k) - g(x_*)| \\ \text{Taylor series} \rightarrow &= \begin{cases} |g'(x_*)| |x_k - x_*| & \text{if multiple root} \\ \frac{1}{2} |g''(x_*)| |x_k - x_*|^2 & \text{if simple root i.e. } f(x) = 0, f'(x) \neq 0 \end{cases} \end{aligned}$$

~~since $g'(x_*) = 0$~~

since for a simple root $g'(x_*) = 0$

but for a multiple root $f(x) = (x - x_*)^m \tilde{f}(x)$

$$\rightarrow g'(x_*) = \frac{m-1}{m} < 1 \neq 0$$

$$\begin{aligned} \rightarrow e_{k+1} &\leq C e_k^1 && \text{for simple, multiple root} \\ &&& \rightarrow \text{linear convergence} \\ e_{k+1} &\leq D e_k^2 && \text{for simple root} \\ &&& \rightarrow \text{quadratic convergence.} \end{aligned}$$

(b) constant C & rate p are defined by relation

$$e_{k+1} \leq C e_k^p$$

\therefore To find p plot $\log e_{k+1}$ vs. $\log e_k$ and fit straight line to find p & C from $\log e_{k+1} = p \log e_k + \log C$.

or, To find C plot $\frac{e_{k+1}}{e_k^p}$ & fit line of slope zero.

3. (a) $f(x^* + \frac{h}{2}) = f(x^*) + f'(x^*) \frac{h}{2} + \frac{1}{2} f''(x^*) \left(\frac{h}{2}\right)^2 + o(h^3)$ = 0 since c.p.

$\therefore h = \text{forward error} \approx \sqrt{\frac{|f(\hat{x}) - f(x^*)|}{\frac{1}{2} |f''(x^*)|}}$

but $|f(\hat{x}) - f(x^*)| = \text{backward error} \equiv \Delta b$

$\rightarrow C = \frac{h}{\Delta b} = \sqrt{\frac{2}{\Delta b |f''(x^*)|}}$

(b) ~~The absolute condition~~

The minimum error is ~~therefore~~ when

$\Delta b = \epsilon_{\text{mach}}$

$\therefore \text{min error} = \sqrt{\frac{2 \epsilon_{\text{mach}}}{|f''(x^*)|}}$
 $= C \epsilon_{\text{mach}}$

\therefore if $|f''(x^*)| = O(1)$ we can find
 min. ϵ , only half the digits
 accuracy of
 available from floating point system.

\therefore we expect to find x^* to only 8 digits
 of accuracy.